

Meet

Wonder Workshop™ Dash
with Geometry Challenges

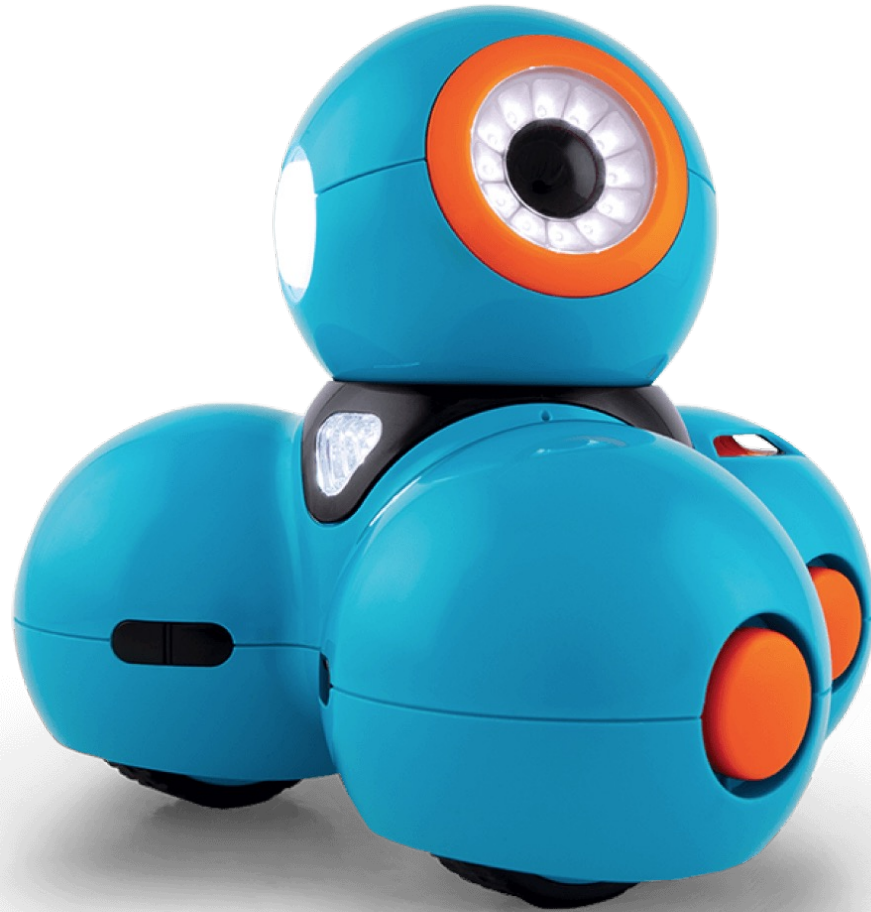
TI-Nspire CXII

Python

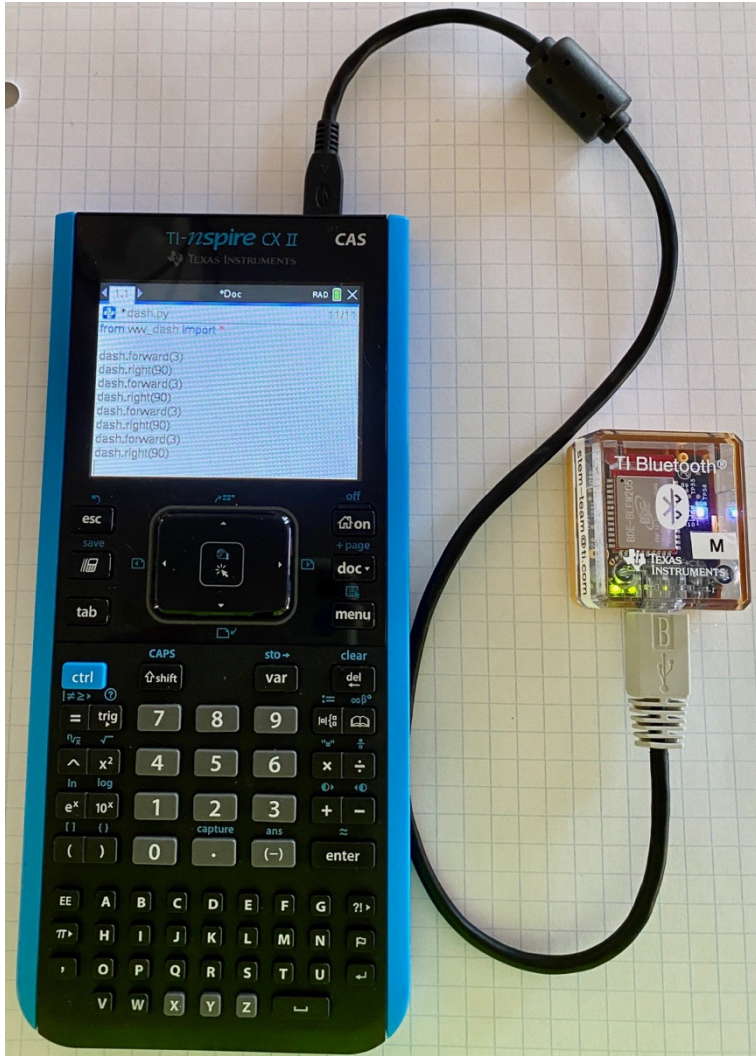
Texas Instruments

@ticalculators

Meet the Wonder Workshop™ Dash



Control the Dash using Python from the TI-Nspire CXII over Bluetooth Wireless

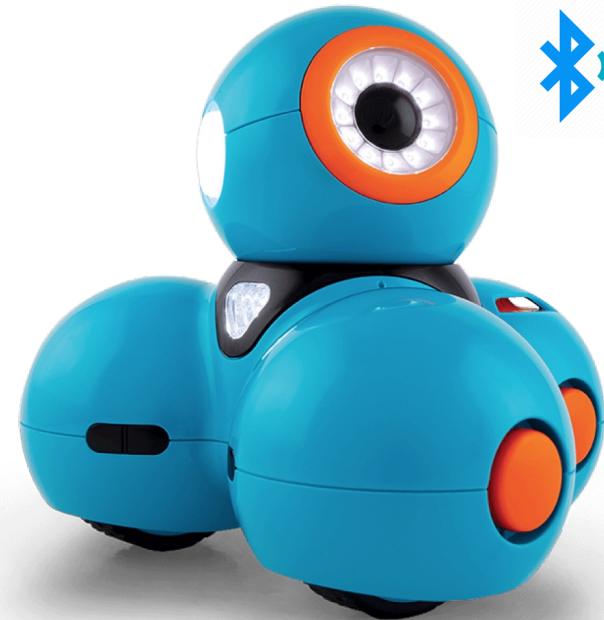


TI-Nspire CXII

TI Bluetooth Adapter



Wonder Workshop™ Dash



Meet the Wonder Workshop™ Dash

User Programmable LED's and Buttons

Customize your experience with Dash

IR Receivers & Transmitters

Enables Dash to find and interact
with other robots

Potentiometers & Dual Motors

Supports head pan and tilt with
accurate positioning

3 Proximity Sensors

Detects objects left, right, and back

Real-time Bluetooth

Fast, easy connections to Apple iOS,
Android and Kindle mobile devices

3x Microphones & Speakers

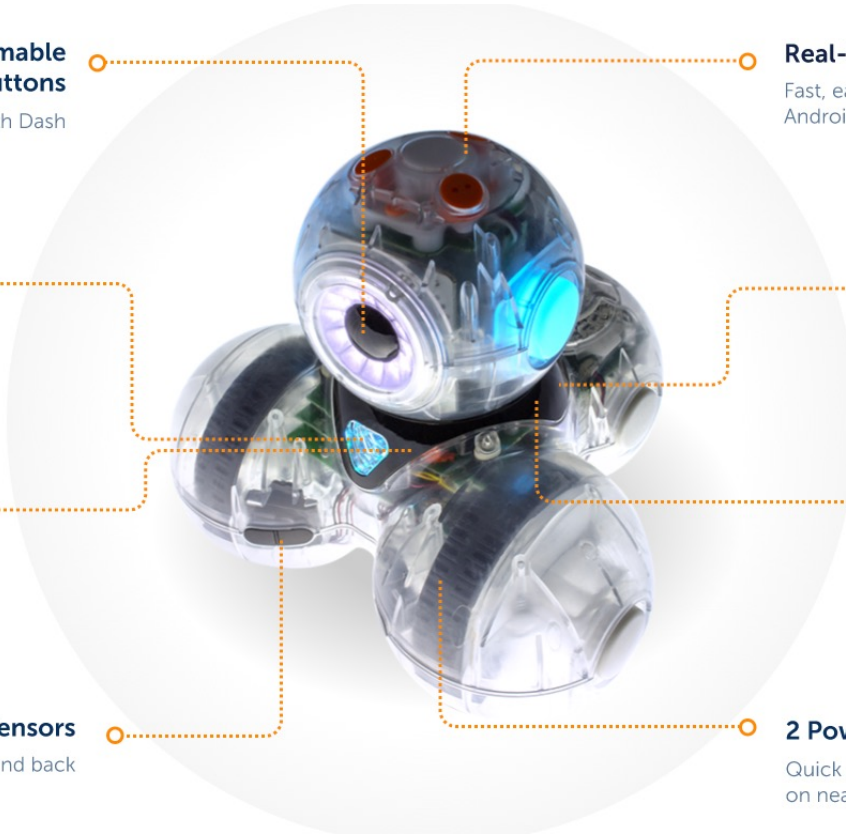
Real-time voice triangulation and
personalized recording and playback

3 Processors & Sensor Fusion

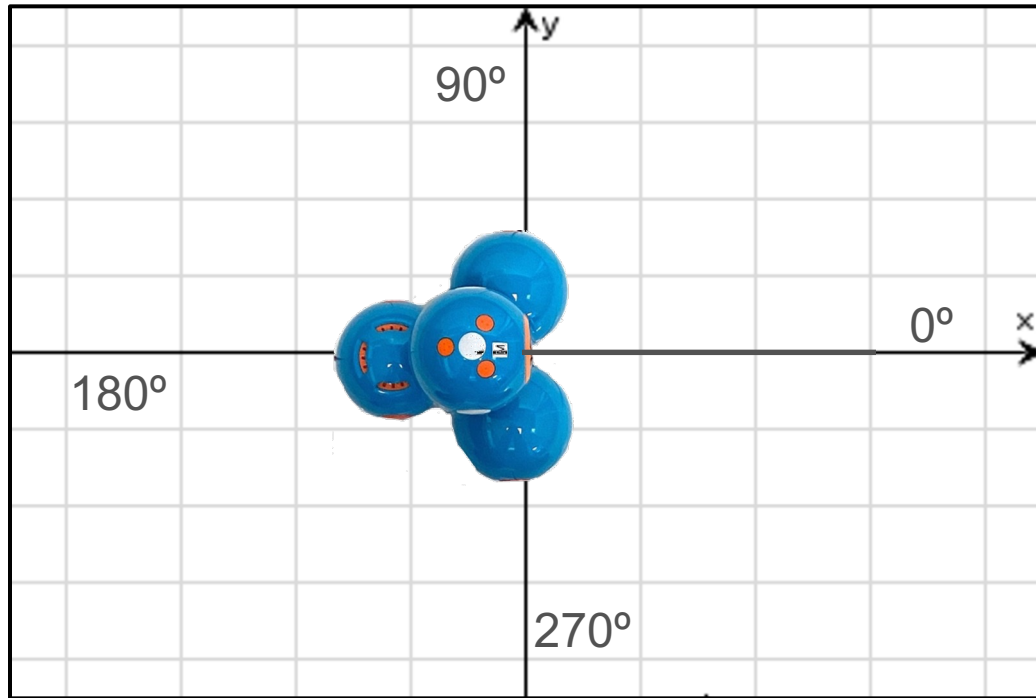
Manages complex interactions among
actuators & sensors - accelerometer,
gyroscope and wheel encoders

2 Powered Wheels

Quick navigation and distance tracking
on nearly any surface



Dash orientation and virtual grid



Dash programs set the initial position as the origin and the heading as 0 degrees measured from the x-axis.

Note: The Dash tracks its position on a virtual coordinate grid with a unit value of 10 cm. The coordinate grid position applies to the `to_xy(x,y)`, `to_polar(r,theta_degrees)` and `to_angle(heading angle, "unit")` functions on the Dash Drive menu. The virtual grid also applies to Path menu functions.

Draw with your Dash

Optional

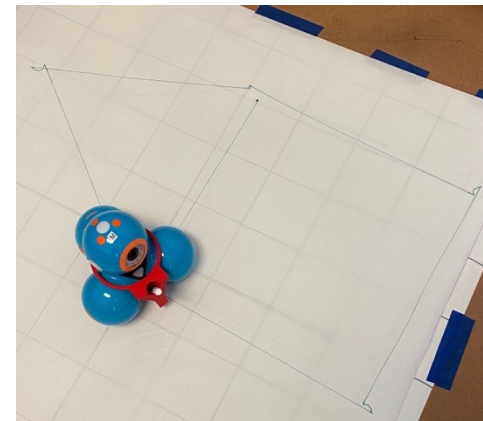


3D Print a snap-on attachment to hold Expo Fine dry erase markers for your Dash.

Step 1: Download .stl file at this [link](#).

Step 2: 3D print following these recommendations.

1. Material PLA
2. Supports not recommended.
3. 20% infill
4. 3 to 4 shells
5. 0.2mm layer height



Setting up your calculator and TI Bluetooth adapter to run Dash

Find step-by-step directions in the Getting Started Guide at education.ti.com/dash

Follow the steps below to put the necessary files onto your calculator and to pair your TI Bluetooth Adapter with a Dash.

1 Download the `ww_dash.tns` Python module file and the `SetDash.tns` file to your calculator using your TI-Nspire computer software or by going to <https://nspireconnect.ti.com/> on your Chrome browser.

2 Open the `ww_dash.tns` file and follow the directions to install the module into the PyLib folder.

3 Plug the TI Bluetooth Adapter into your calculator.



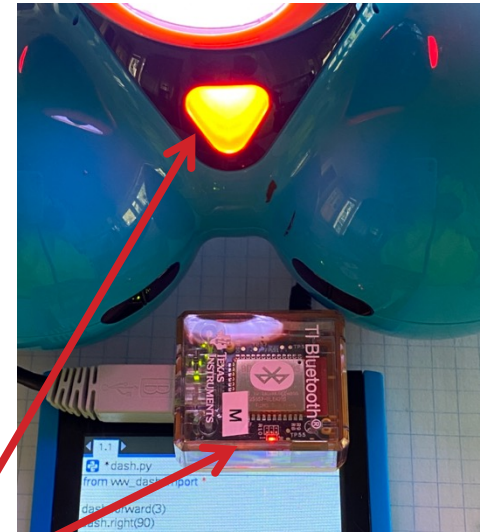
4 Turn on a Dash.
Open the `SetDash.tns` file and follow the directions to search for and select a Dash to pair with the TI Bluetooth Adapter.

The Adapter “remembers” the Dash that it is paired with until you use the `SetDash.tns` file to make a change.

Students can share a Dash by passing a paired Adapter to plug into their calculator.

Use stick-on letters or names to identify Dash/Adapter pairs (“M” is used in the photo.)

Note: The color of the adapter LED and the paired Dash LED’s match (Red in the Photo). Use the `SetDash` setup program to control the Dash color.



5 Quit the `SetDash` setup program.
You are now ready to write and run Python programs to control the Dash.

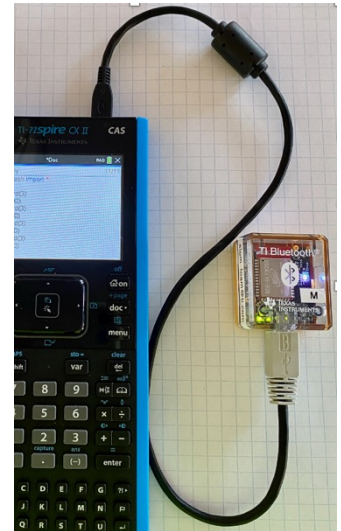
Getting ready to run a Dash program

1 Make sure that your Dash is switched on.



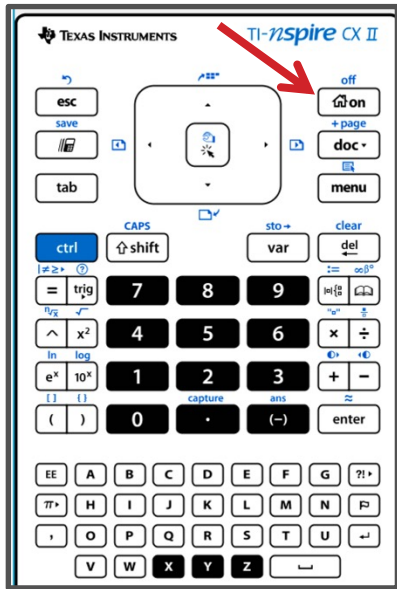
2 Plug the Bluetooth Adapter that is paired with the Dash into the calculator.

You are now ready to run Python programs that control the Dash.



Creating a new TI-Nspire document

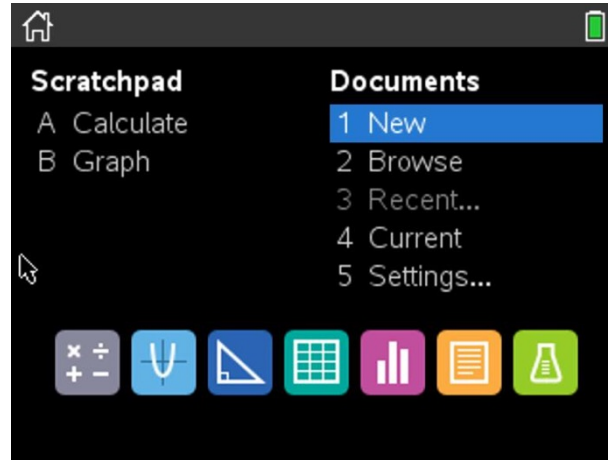
1



Press the **[home/on]** key to display the home screen.

Note: If you have a document open, pressing the **[home/on]** key repeatedly toggles between the home screen and the document.

2



Use **arrow keys** and **[enter]** or Press **[1]** to select 1 New document.

3



See next slide for steps to add a program.

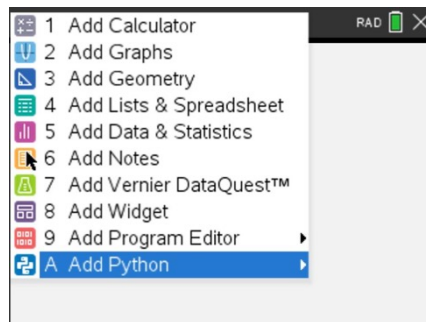
Creating a Dash Program

1



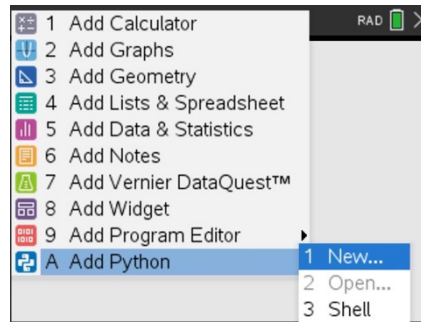
Press **[menu]** to bring up a menu of applications to add to the page.

2



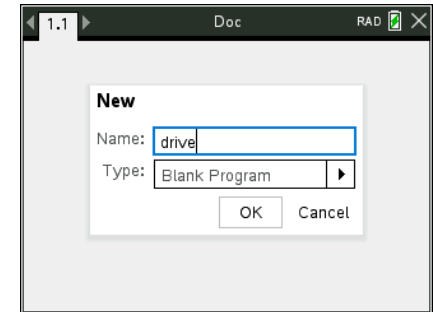
Press **down arrow** repeatedly then press **[enter]** or press **[A]** to select Add Python.

3



Select 1: New by pressing **[enter]** or **[1]**

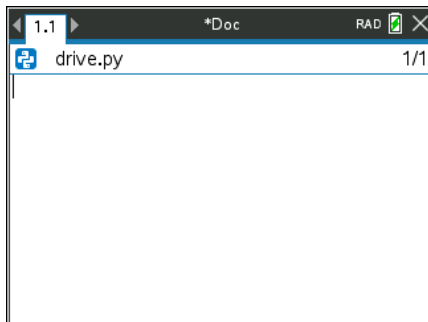
4



Enter your program name and press **[enter]**.

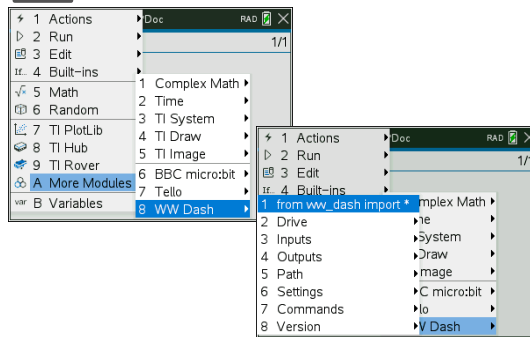
Note: You can also add a new page to the document by pressing **[ctrl] [doc] +page**.

5



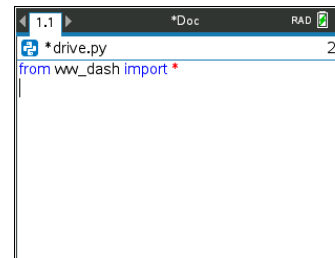
You begin at a blank edit screen.

6



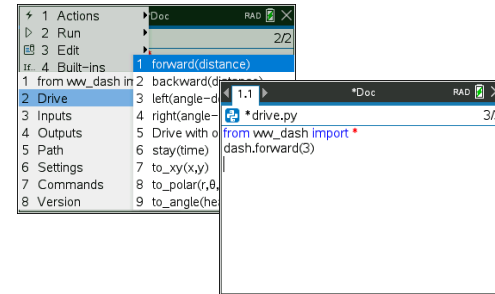
Press **[menu]** then **[A] More Modules** then select **WW Dash** from the More Modules menu. Then select **[1] from ww_dash import *** (Note: The More Modules menu selections depend on the modules that you have added to your calculator.)

7



Importing the `ww_dash` module is required at the beginning of every Dash program.

8

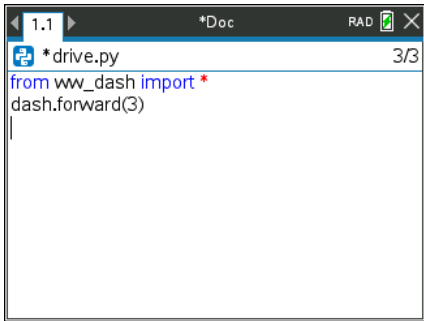


Press **[menu]** then **[A] More Modules** then select **WW Dash** then **[2] Drive** **[1] forward()** to paste to the edit line. Type a value for units to drive. **Right arrow** to the end of the line and press **[enter]** to complete the statement.

A faster approach is to use **[ctrl] [enter]** from any place on a line to complete the statement and move the cursor to the beginning of the line below. **Note:** It is important that each statement begin on a new line.

Running a Dash Program

1



```
*drive.py 3/3
from ww_dash import *
dash.forward(3)
```

Press **[ctrl] [R]** to run the program from a Python shell on the next page.

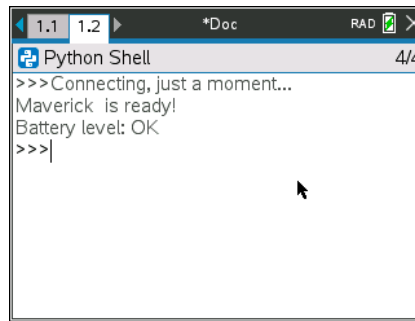
Note: **[ctrl] [R]** also checks syntax and stores program changes. **[ctrl] [B]** is another option for checking syntax and storing.

* before the program name indicates that changes have not been stored.

Before running the program make sure that

- Dash is switched on
- Bluetooth Adapter is connected to the calculator
- Dash is on a flat surface ready to roll

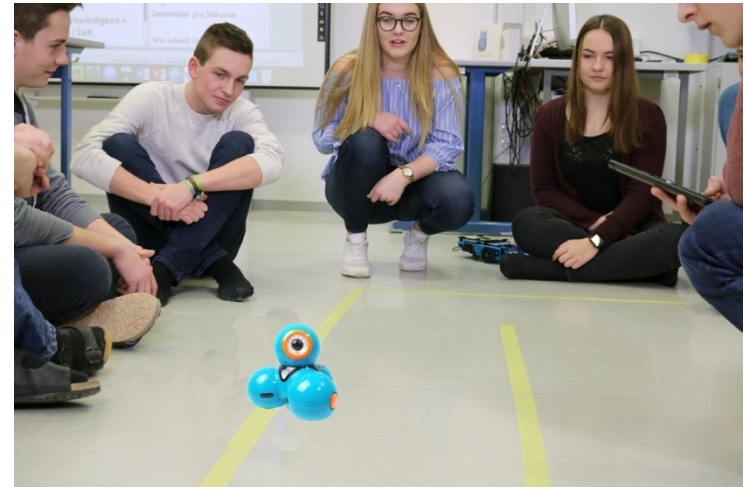
2



```
Python Shell 4/4
>>>Connecting, just a moment...
Maverick is ready!
Battery level: OK
>>>|
```

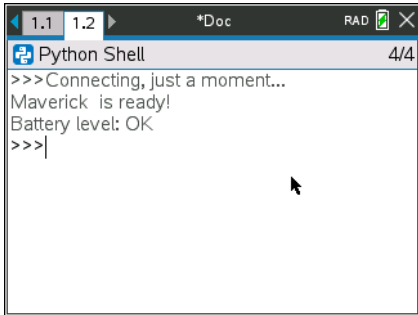
Your program runs in a Python shell.

You can re-run the program from the shell by pressing **[ctrl] [R]** again.



Editing a Dash Program

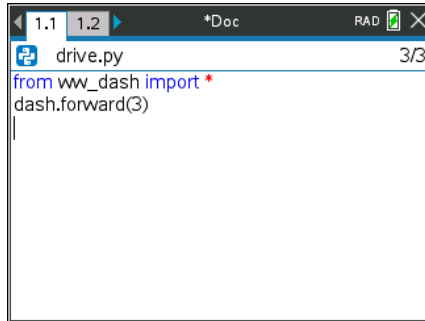
1



```
Python Shell 4/4
>>>Connecting, just a moment...
Maverick is ready!
Battery level: OK
>>>|
```

Press **[ctrl] left** to go back to your Python editor page.

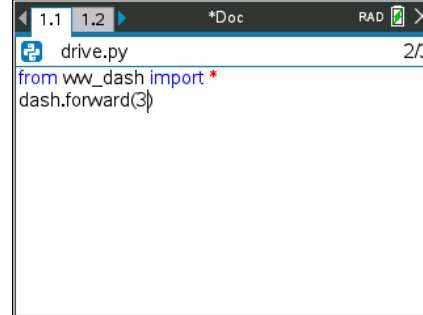
2



```
drive.py 3/3
from ww_dash import *
dash.forward(3)
|
```

Use the arrow keys to position the cursor to change the value of the forward distance.

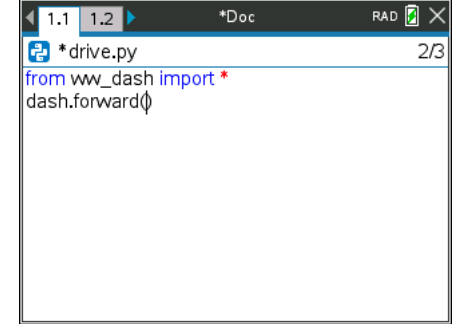
3



```
drive.py 2/3
from ww_dash import *
dash.forward( )
```

Press **[del]** to backspace over the 3.

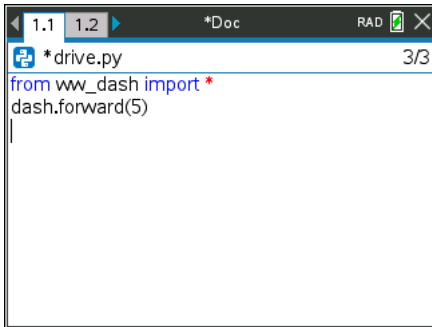
4



```
*drive.py 2/3
from ww_dash import *
dash.forward( )
|
```

Type in a new value for distance, then **[ctrl] [enter]** to move to the next line.

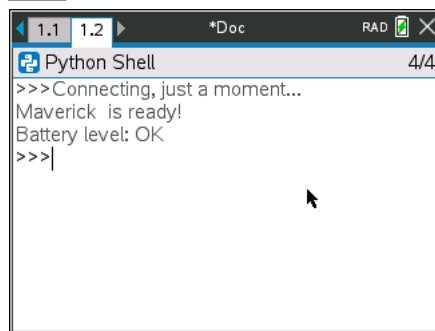
5



```
*drive.py 3/3
from ww_dash import *
dash.forward(5)
|
```

Press **[ctrl] [R]** to run the program again from a Python shell on the next page.

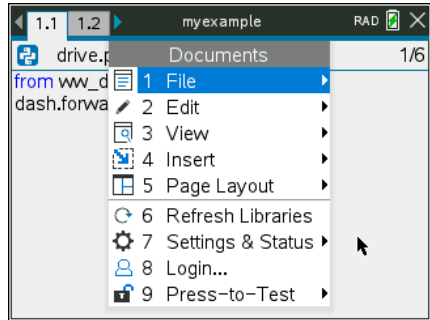
6



```
Python Shell 4/4
>>>Connecting, just a moment...
Maverick is ready!
Battery level: OK
>>>|
```

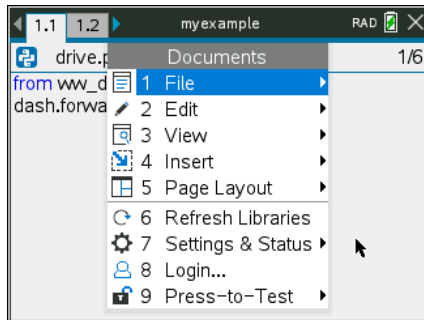

Saving a TI-Nspire document file

1



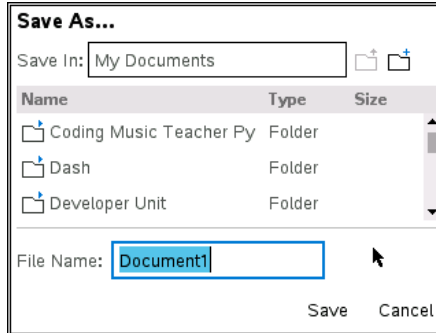
Press **[doc]** then select 1 File from the menu by pressing **[enter]** or **[1]**.

2



Select 4 Save or 5 Save As... from the menu.

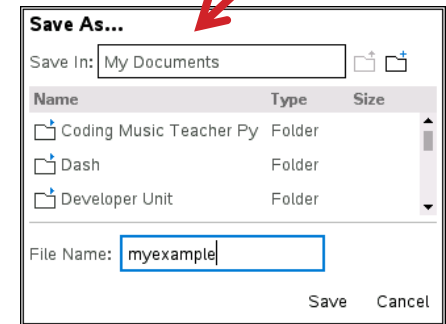
3



Type in your file name using alpha and numeric characters.

Note: The name must begin with an alpha character.

4



Folder where file will be saved.

Press **[enter]** to save the file to the folder indicated above.

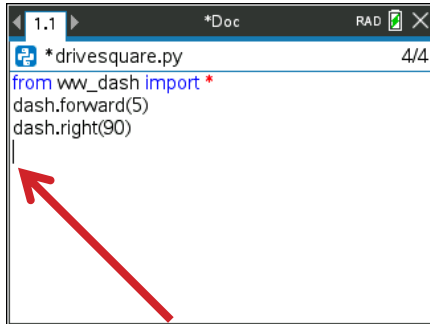
To change the folder press the **[UP]** arrow key and then use **arrows** and **[enter]** to select a folder before pressing **[enter]** to save the file.

Press **[esc]** to cancel the save dialogue.

You can use **[ctrl] [S]** as a shortcut to save the TI-Nspire document file.

Copying and Pasting a Block of Code

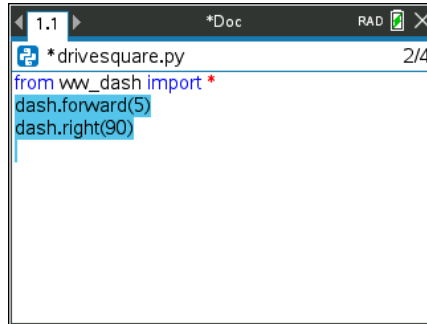
1



```
*drivesquare.py 4/4
from ww_dash import *
dash.forward(5)
dash.right(90)
```

Use **arrow keys** to move the cursor to the beginning of row below the section of code that you want to copy.

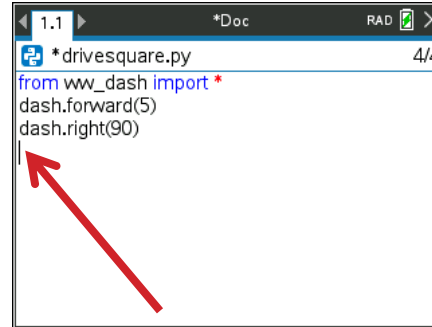
2



```
*drivesquare.py 2/4
from ww_dash import *
dash.forward(5)
dash.right(90)
```

Press and hold **[shift]** then press **UP arrow** repeatedly to highlight the rows to be copied. Press **[ctrl] [C]** to copy the highlighted code.

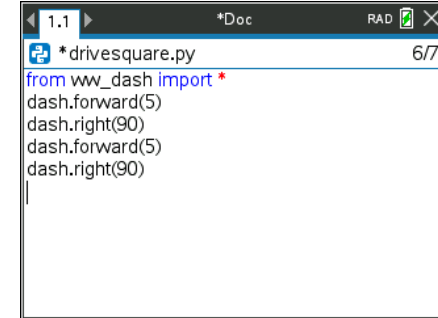
3



```
*drivesquare.py 4/4
from ww_dash import *
dash.forward(5)
dash.right(90)
```

Use **arrow keys** to move the cursor to the location that you want to paste from.

4



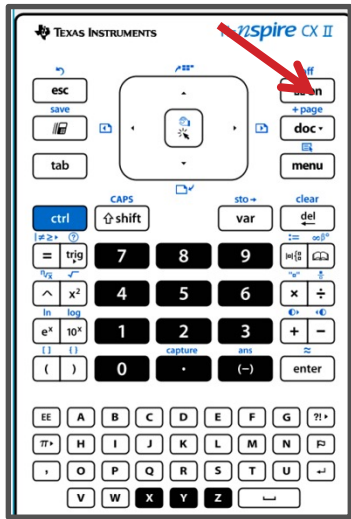
```
*drivesquare.py 6/7
from ww_dash import *
dash.forward(5)
dash.right(90)
dash.forward(5)
dash.right(90)
```

Press **[ctrl] [V]** to paste.

You can paste repeatedly.

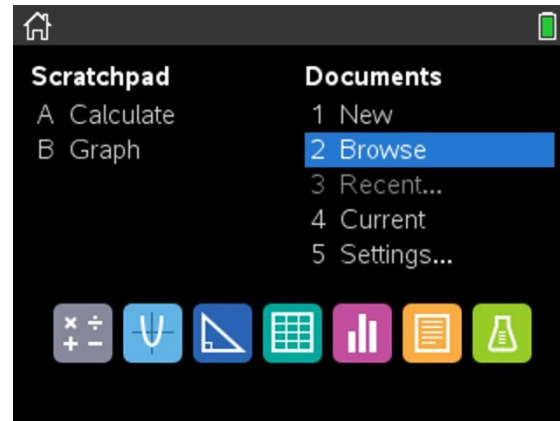
Opening an existing TI-Nspire document file

1



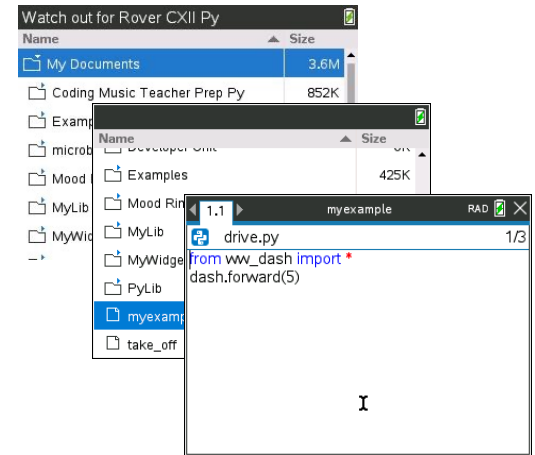
Press the **[home/on]** key to display the home screen.

2



Use **arrow keys** and **[enter]** or Press **[2]** to select 2 Browse files.

3

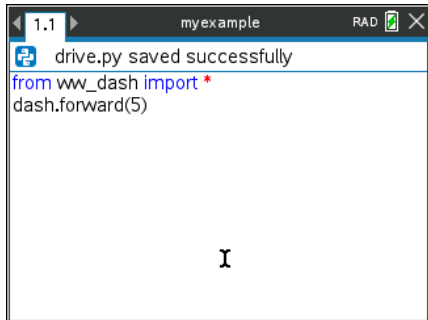


Use **arrow keys** and **[enter]** to select a folder and a file.

Note: Pressing the **[home/on]** key repeatedly toggles between the home screen and the current document.

Copying a Python Program

1

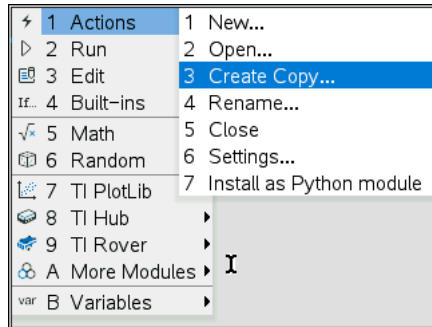


```
drive.py saved successfully
from ww_dash import *
dash.forward(5)
```

Press **[ctrl] [B]** to compile and save your program.

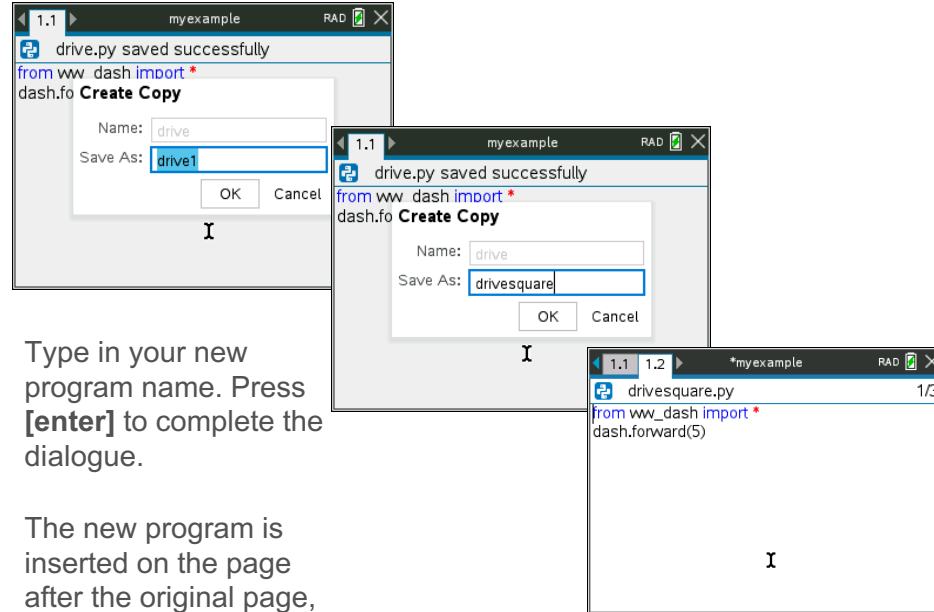
Note: You will not be able to copy the program if you have made changes since using **[ctrl] [R]** or **[ctrl] [B]**.

2



Press **[menu] [1]** Actions
[3] Create Copy...

3

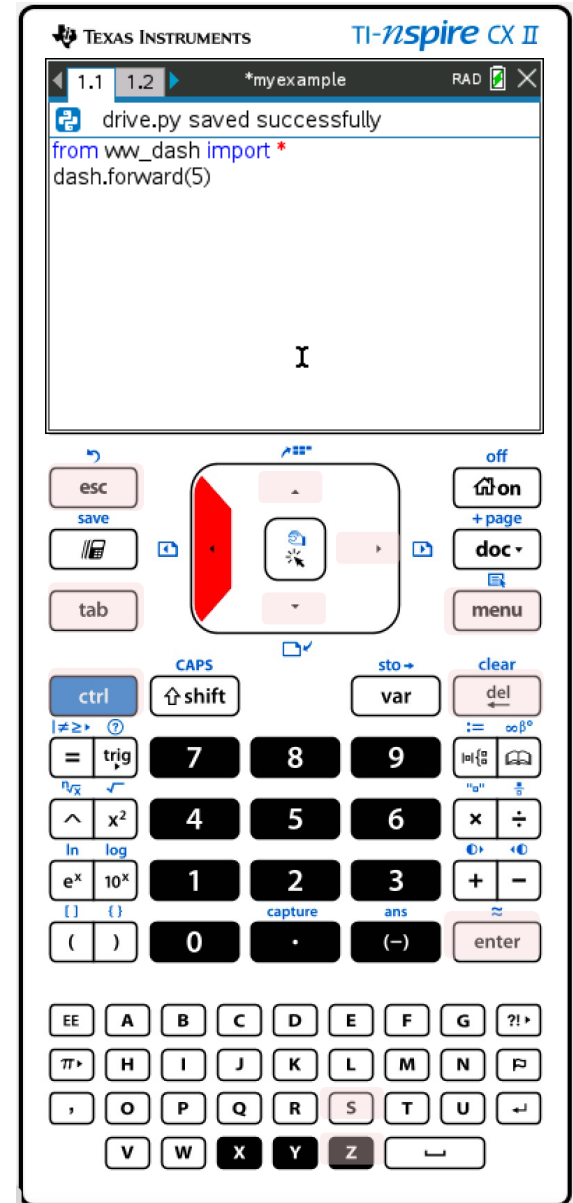


Type in your new program name. Press **[enter]** to complete the dialogue.

The new program is inserted on the page after the original page, in this case page 1.2.

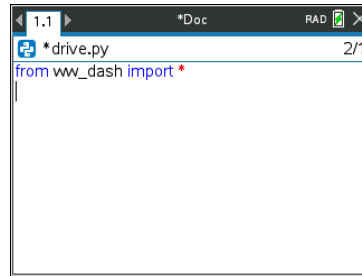
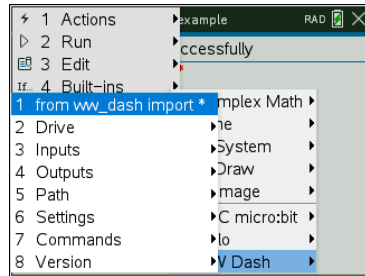
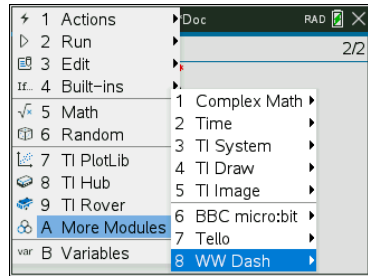
Entry and Edit Tips

- » Use **number key shortcuts** or **arrow keys** and **[enter]** to select from menus
- » Use **[esc]** to back out of a menu or a dialogue.
- » Use **[enter]** to complete a dialogue.
- » Use **[tab]** to move to the next input when entering a function
- » Use **arrow keys** to move the cursor around the screen
- » Use **[del]** as a destructive backspace
- » Use **[ctrl] [enter]** to complete a statement and move to the next line
- » Use **[ctrl] [Z]** to undo an action
- » Use **[ctrl] [S]** to save your file
- » Use **[ctrl] [left arrow]** and **[ctrl] [right arrow]** to move from page to page
- » Use **[menu]** to see options for the current application.

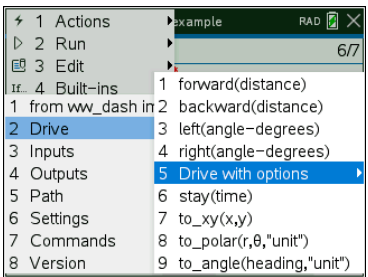


Dash Module Menus

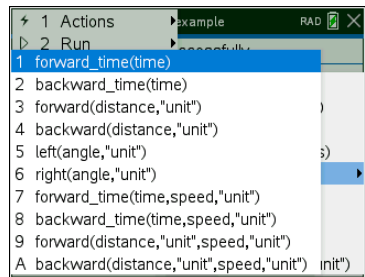
Find **from ww_dash import *** on the **A: More Modules WW Dash** menu. Every Dash program must include a `ww_dash` import statement. This statement imports Dash Python functions.



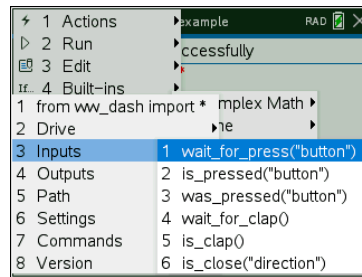
Drive



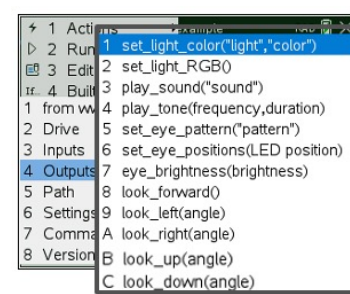
Drive with options



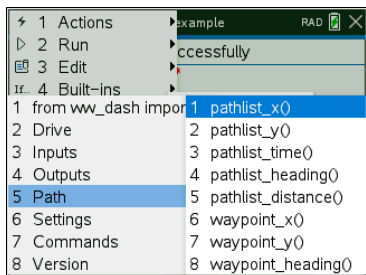
Inputs



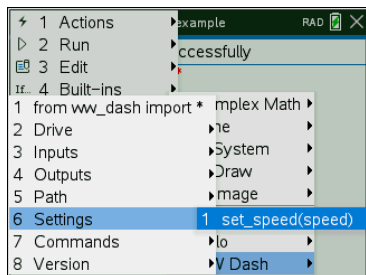
Outputs



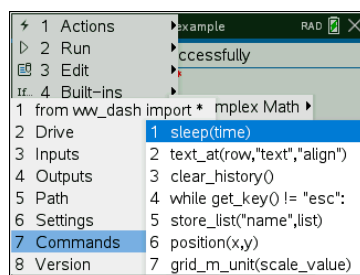
Path



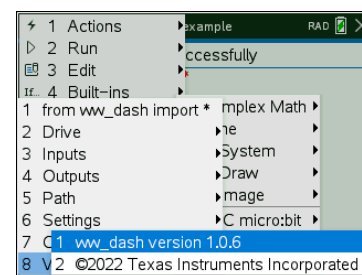
Settings



Commands

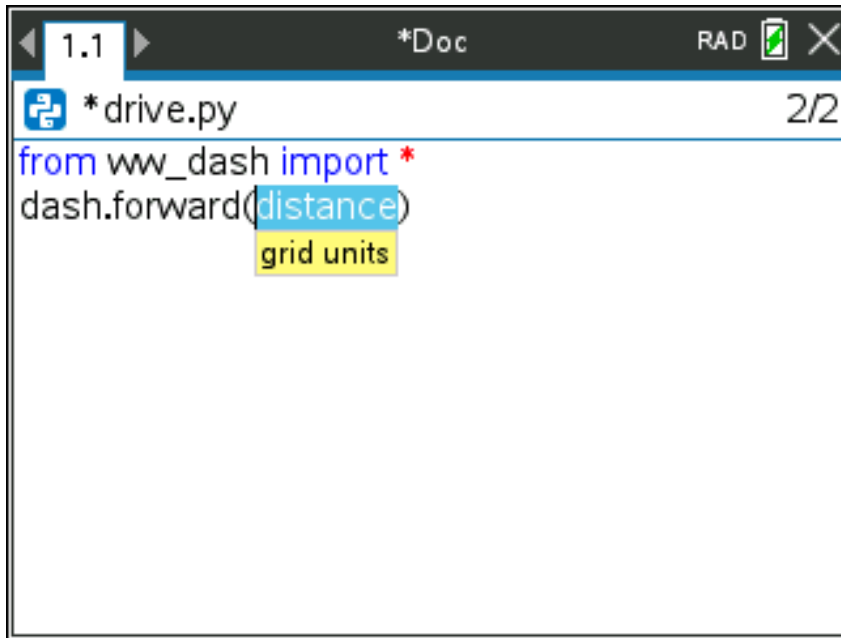


Version



MAKE IT MOVE!

New Program:



```
1.1 *Doc RAD [icon] X
*drive.py 2/2
from ww_dash import *
dash.forward(distance)
```

Press **[menu]** key to see Python Program Editor options.

Press **[ctrl] [R]** to run the program from a Python shell on the next page.

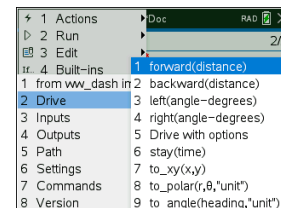
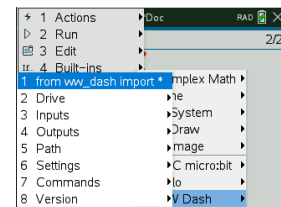
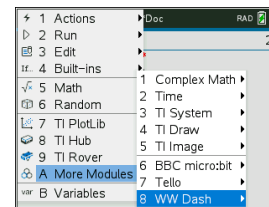
Use **[ctrl] left arrow** to move from the shell page back to the Python editor page.

Task: Discover how far Dash drives per unit.

Use differing values (1-20) to determine what 1 Dash unit is.


Find `from ww_dash import *` on the A: More Modules WW Dash menu.

Find `forward()` and other drive functions on the WW Dash 2:Drive menu.



Have Dash make a sound

Edit Program:



```
1.4 1.5 1.6 *meetdas...her RAD X  
*drivesound.py 4/20  
from ww_dash import *  
dash.play_sound("Dinosaur")  
dash.forward(4)
```

To insert a blank line for the `play_sound()` function move the cursor to the `ww_dash import` line and then press **[ctrl] [enter]**

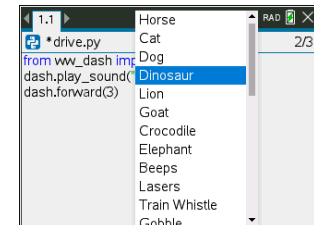
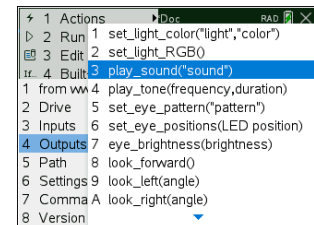
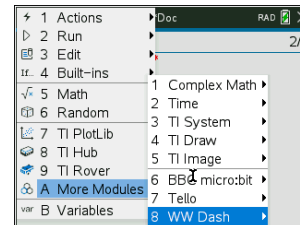
Press **[ctrl] [R]** to run the program from a Python shell on the next page.

Use **[ctrl] left arrow** to move from the shell page back to the Python editor page.

Task: Have your Dash play a sound while driving.


Challenge Task: Have your Dash make a “Fire Siren” sound.

Find `dash.play_sound()` on the A: More Modules WW Dash 4:Outputs menu. After you paste the function to the editor you will be prompted to select a sound from a drop-down menu.



Set the Dash color

New Program:



```
from ww_dash import *
dash.set_light_RGB("all",255,0,0)
```

Find `dash.set_light_RGB()` on the WW Dash 4:Outputs menu. You will be prompted for the lights to set and then the values of the red, green and blue components of the LED, 0 is off and 255 is maximum. Press **[tab]** to move from input to input. Finally, press **[ctrl] [enter]** to complete the statement and move to the next line.

Press **[ctrl] [R]** to run the program from a Python shell on the next page.

Use **[ctrl] left arrow** to move from the shell page back to the Python editor page.

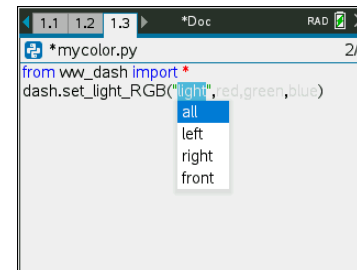
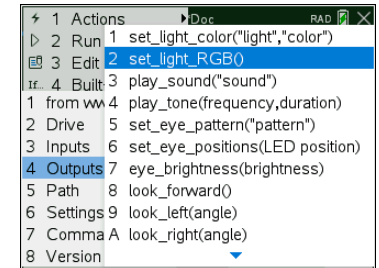
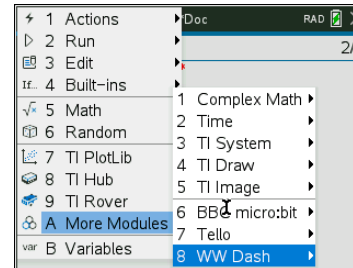
Task: Set the color output of the Red, Green, Blue (RGB) LED.

Each color takes a value of (0-255).

Challenge Tasks:

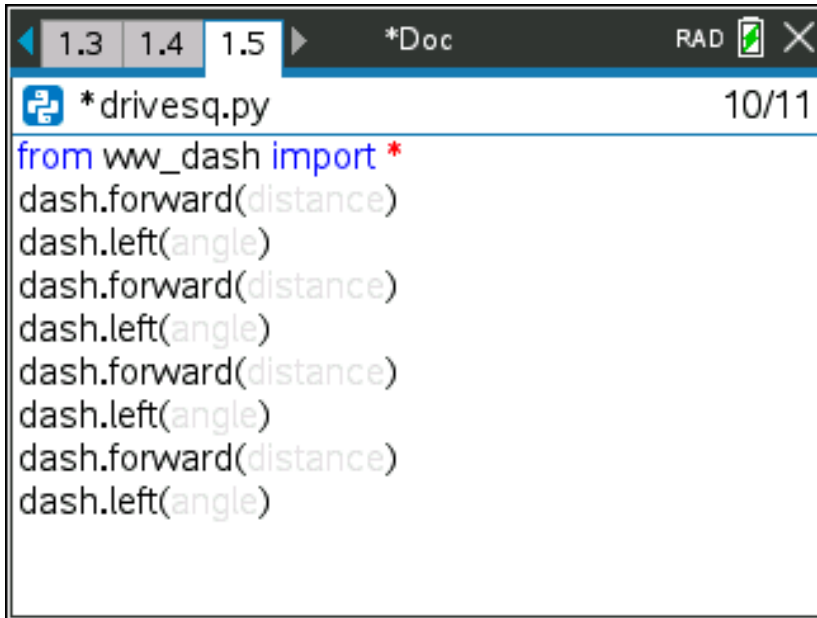
Try to make **Yellow** or **Cyan** or **Magenta**.

Extra Challenge: Make your own color and give the color a fun name.



Explore angles

New Program:



```
from ww_dash import *
dash.forward(distance)
dash.left(angle)
dash.forward(distance)
dash.left(angle)
dash.forward(distance)
dash.left(angle)
dash.forward(distance)
dash.left(angle)
```

The program above is a framework for driving a square.
Enter values for distance and turn angle.

Press **[menu]** key to see Python Program Editor options.

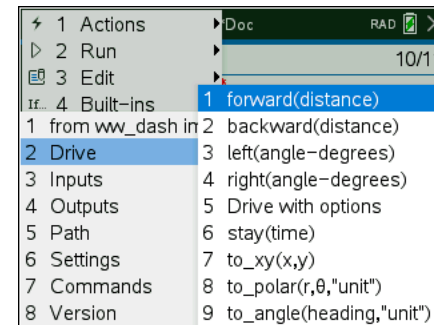
Press **[ctrl] [R]** to run the program from a Python shell on the next page.

Use **[ctrl] left arrow** to move from the shell page back to the Python editor page.

Task: Drive a square.

Challenge Task: Try to drive an equilateral triangle.

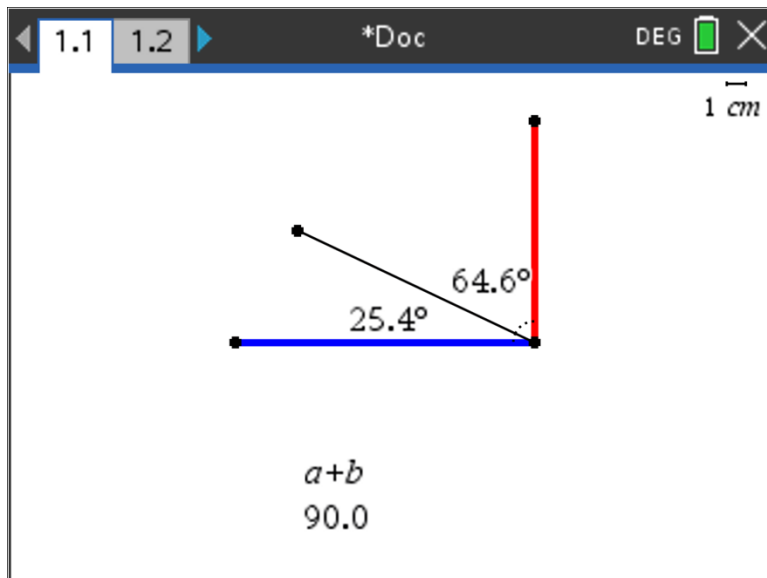
See the menu for the most common drive functions below.



Quick Math Reminders

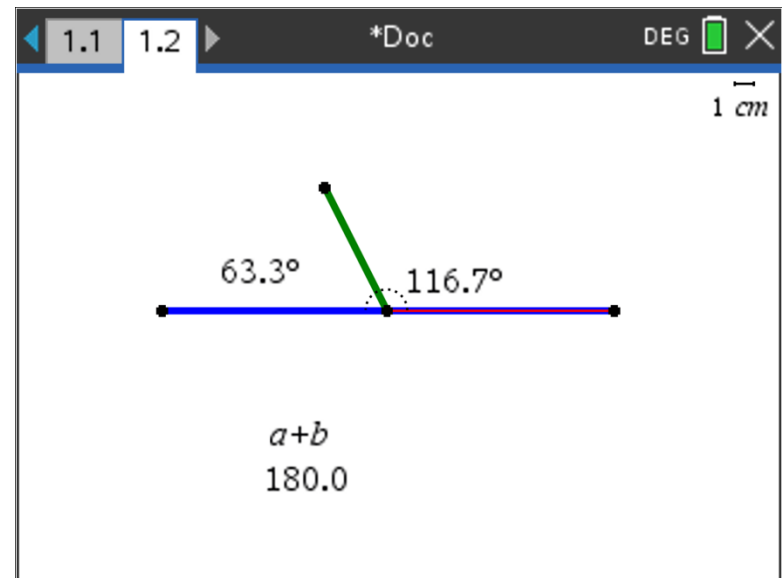
» Complementary Angles:

» Sum to 90 degrees



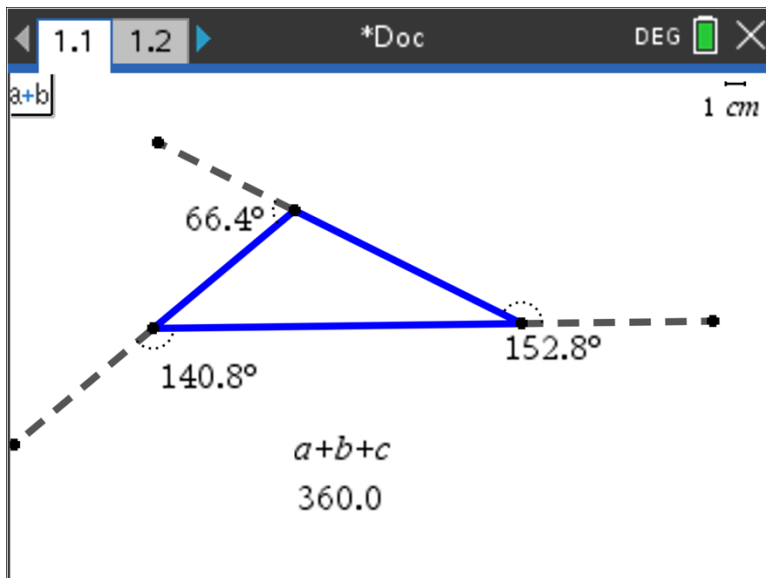
» Supplementary Angles:

» Sum to 180 degrees

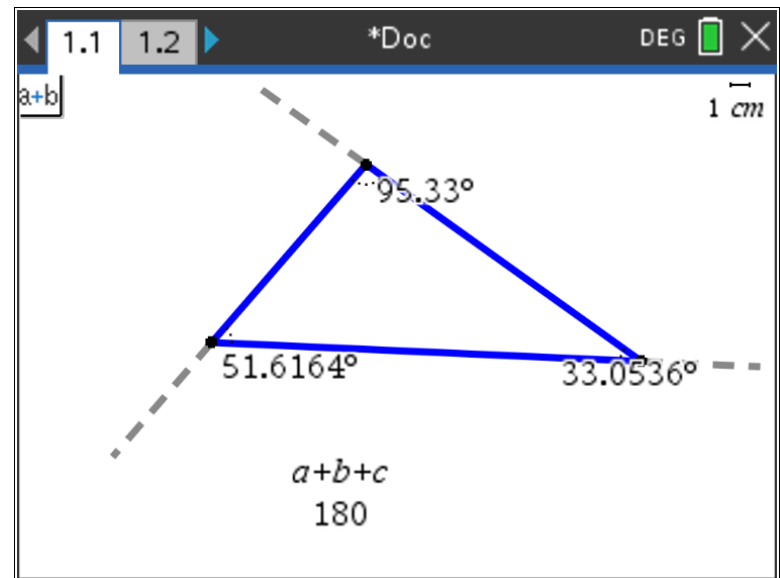


Quick Math Reminders

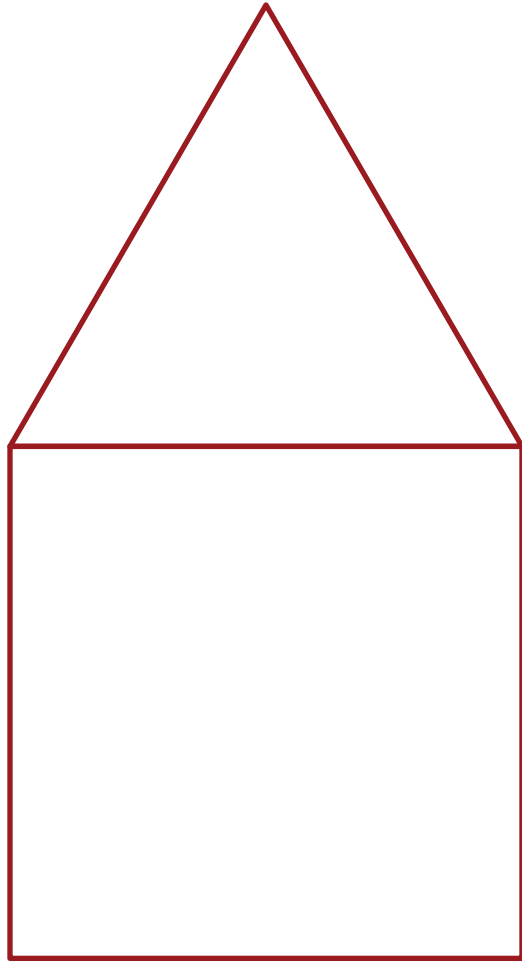
» Exterior angles:



» Interior Angles:



Logic Challenge

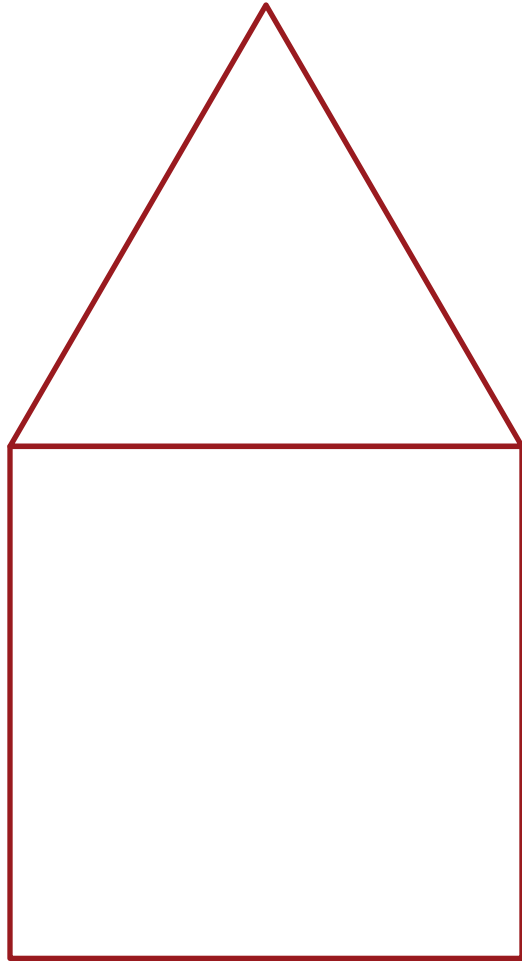


Task: Draw the figure shown large enough for Dash to drive.

Note: Try side lengths of 4 Dash units.

Write a program to have your Dash drive the figure without crossing any lines or going back over a line.

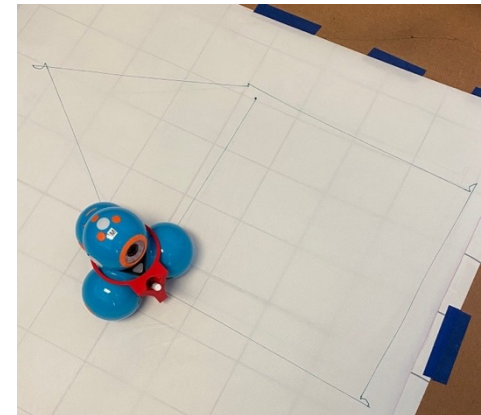
Logic Challenge



Task: Drive the figure shown without crossing any lines or going back over a line and without picking up the pen.

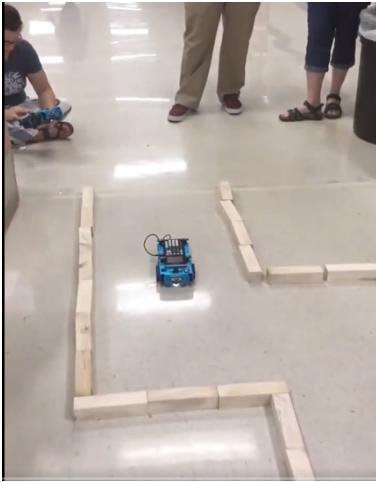
Note: Try side lengths of 4 Dash units.

When you are ready, put the pen in and trace your path.

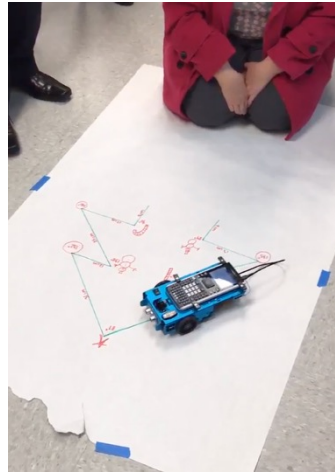


Note: For more information about marker holder 3D
Print file see the earlier slide in this deck.

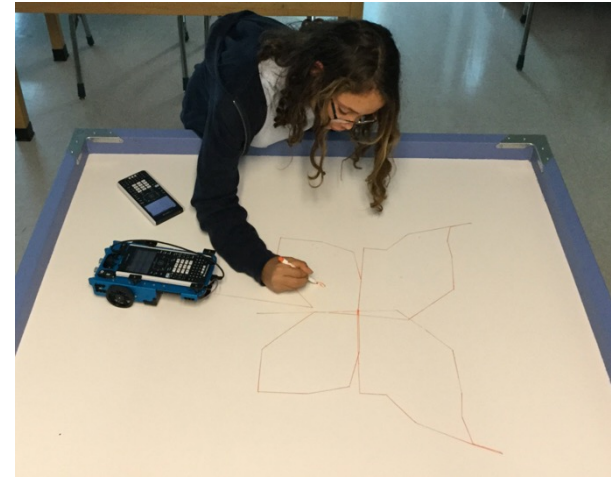
Where can you go next with TI-Rover and Dash?



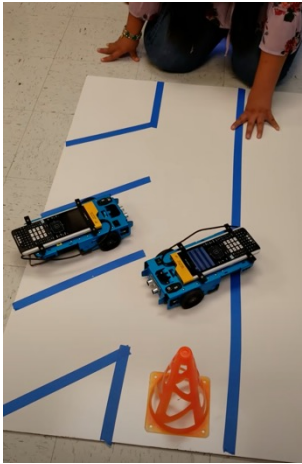
Drive an obstacle course



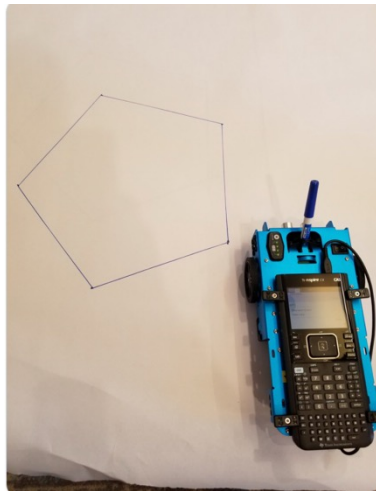
Drive a design



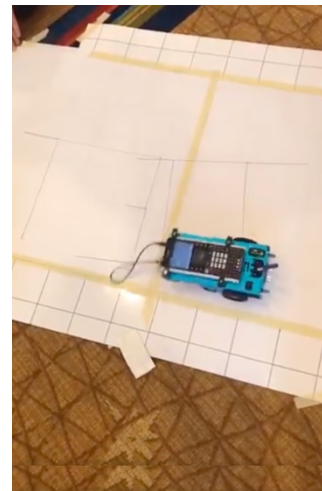
Draw artwork



Park your Rover



Use a For loop
to draw polygons



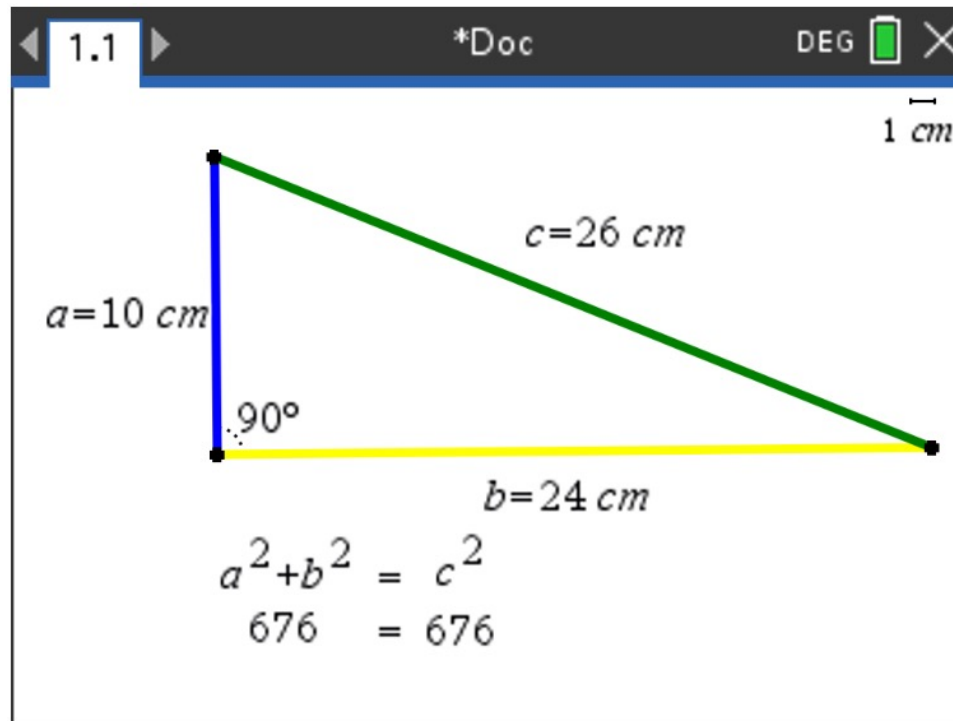
Write your name



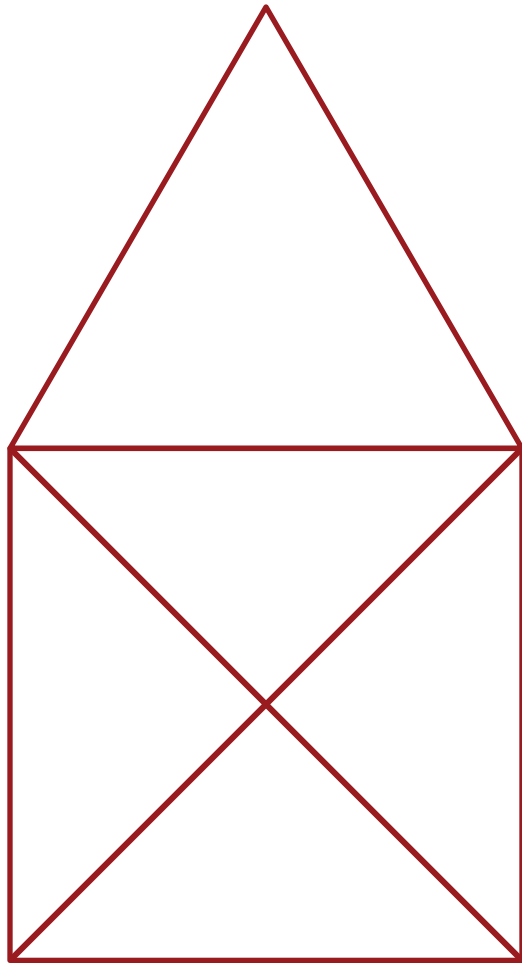
Navigate a map

Quick Math Reminders

» Pythagorean Theorem



Logic Challenge 2



Task: Draw the figure shown large enough for Dash to drive.

Write a program to have your Dash drive the figure without crossing any lines.

The Math Module is needed for Square Root and other advanced functions.

The image shows two screenshots from a TI-OS interface. The left screenshot shows a menu with 'Math' selected, and a sub-menu listing functions like 'sqrt()'. The right screenshot shows a code editor with Python code for Dash robot control.

```
1 from math import *
2 Const
3 Trig
4 fabs()
5 sqrt()
6 exp()
7 pow(x,y)
8 log(x,base)
9 fmod(x,y)
A ceil()

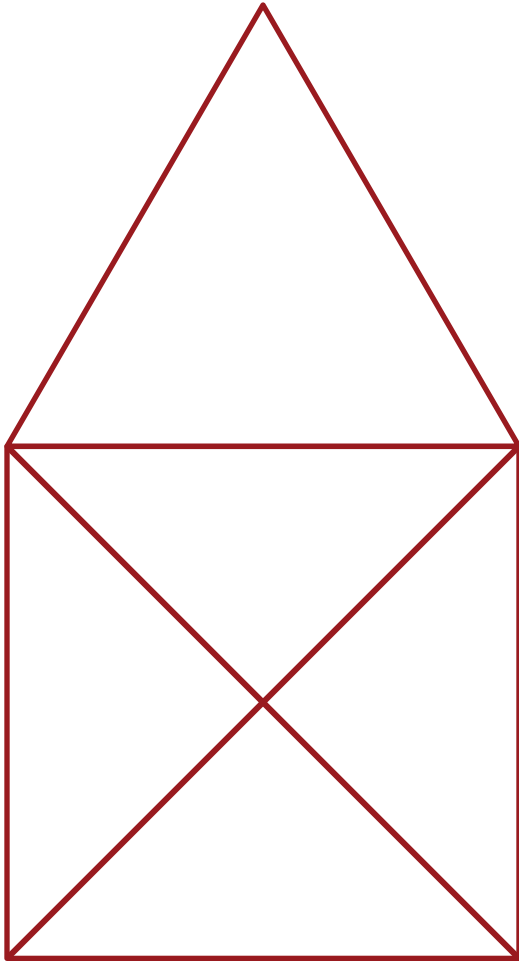
1.16 1.17 1.18 *meetdas...ent RAD 7/33
*challenge2.py 7/33
from ww_dash import *
from math import *

dash.forward(4)
dash.right(30)
dash.forward(4)
```

Logic Challenge 2

Task: Drive the figure shown without crossing any lines or going back over a line and without picking up the pen.

When you are ready, put the pen in and trace your path.

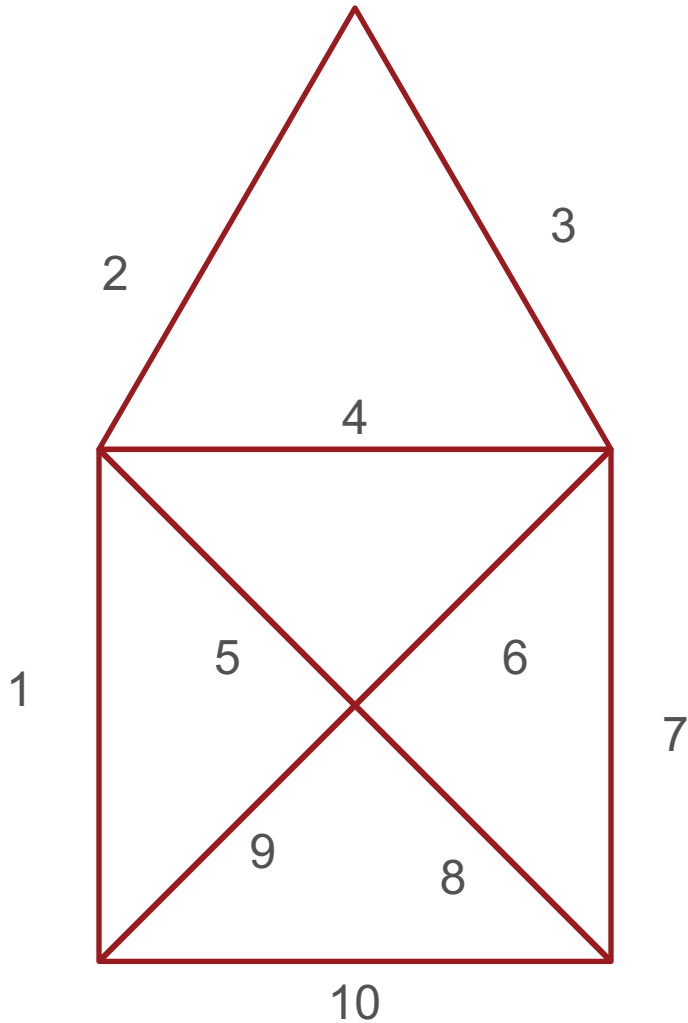


Note: For more information about marker holder 3D Print file see the earlier slide in this deck.

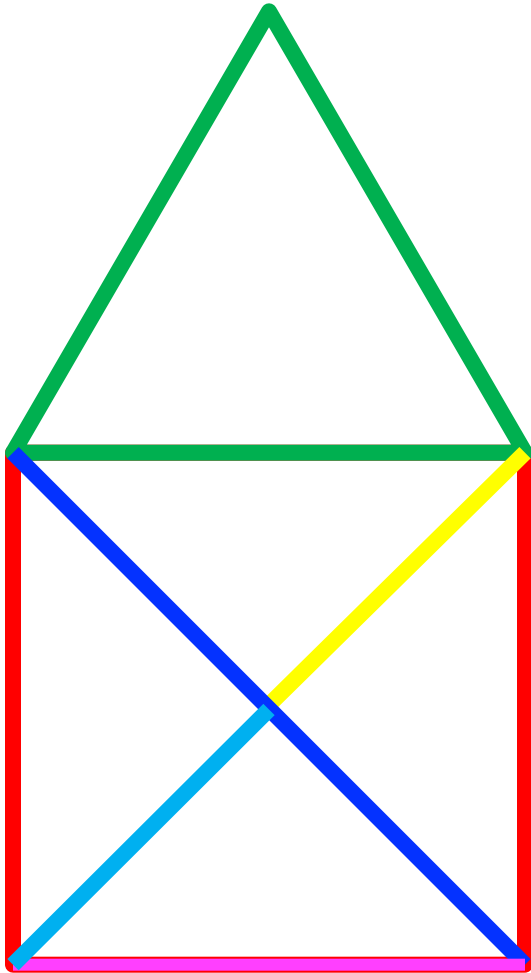
The Math Module is needed for Square Root and other advanced functions.

<ul style="list-style-type: none"> ⚡ 1 Actions ▶ 2 Run ✎ 3 Edit ℹ 4 Built-ins √ 5 Math 📦 6 Random 📊 7 TI PlotLib 🌐 8 TI Hub 🚗 9 TI Rover 🔗 A More Modules var B Variables 	<pre> 1 from math import * 2 Const 3 Trig 4 fabs() 5 sqrt() 6 exp() 7 pow(x,y) 8 log(x,base) 9 fmod(x,y) A ceil() </pre>	<pre> 1.16 1.17 1.18 *meetdas...ent RAD X *challenge2.py 7/33 from ww_dash import * from math import * dash.forward(4) dash.right(30) dash.forward(4) </pre>
--	--	---

Logic Challenge 2 – example solution



Logic Challenge 3



Task: Drive the figure shown without crossing any lines or going back over a line.

Now match the colors using the RGB LED. Don't worry about using a marker.

The Math Module is needed for the Square Root Function.

Put the `set_light_RGB` statement before the drive statement that you want to match.
Note: The LED's stay the same color until another `set_light_RGB` statement is run.

```
1 Actions
2 Run
3 Edit
4 Built-ins
5 Math
6 Random
7 TI PlotLib
8 TI Hub
9 TI Rover
A More Modules
var B Variables
```

```
1 from math import *
2 Const
3 Trig
4 fabs()
5 sqrt()
6 exp()
7 pow(x,y)
8 log(x,base)
9 fmod(x,y)
A ceil()
```

```
1.20 1.21 1.22 *meetdas...ent RAD 9/35
*challenge3.py
from ww_dash import *
from math import *

dash.set_light_RGB("all",255,0,0)
dash.forward(4)
dash.set_light_RGB("all",0,255,0)
dash.right(30)
dash.forward(4)
```


Thank You



www.TIstemProjects.com

Contact stem-team@ti.com with questions